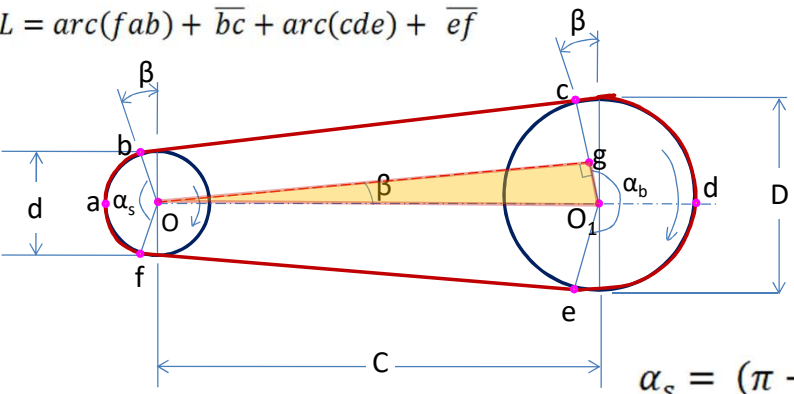
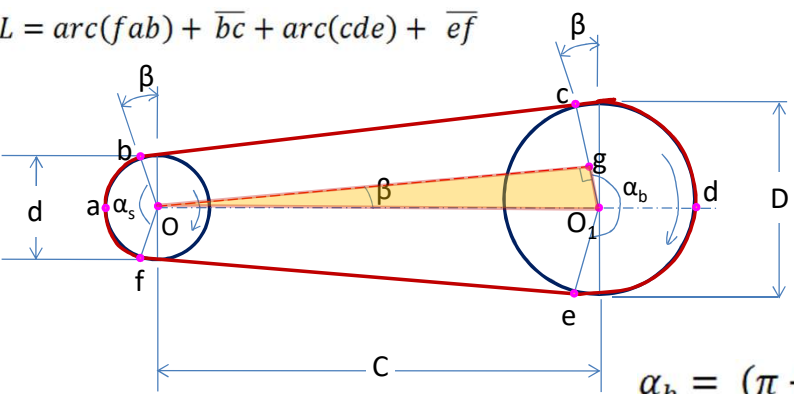
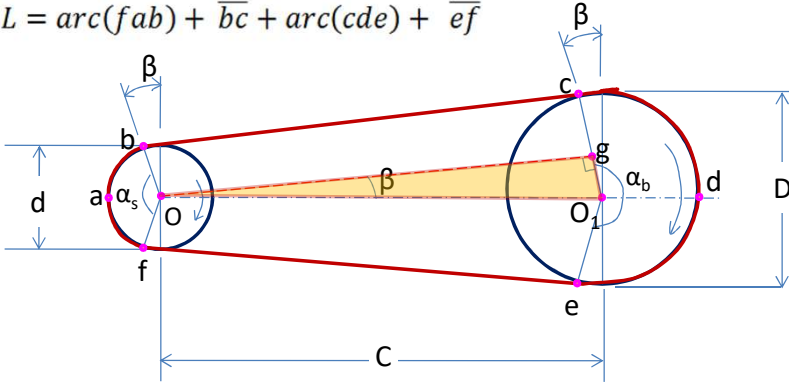


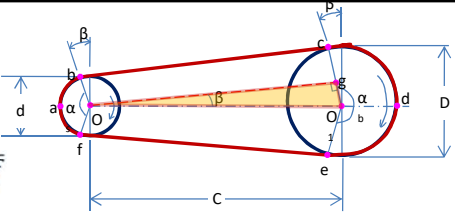
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| | <p style="text-align: center;">Belt Drives</p> <p>There are two types of drives rigid and flexible. Gear drives are called as rigid or non flexible drives. Belt, chain and rope drives are called as flexible drives. In flexible drives there is a intermediate link such as belt, chain or rope in-between the driving and driven shafts.</p> |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>Advantages of flexible drives over rigid drives are as follows:</p> <ol style="list-style-type: none"> i) Flexible drives transmit power over a comparatively long distance due to an intermediate link between driving and driven shafts. ii) Since the intermediate link is long and flexible, it absorbs shock loads and damps vibrations. iii) Flexible drives provide considerable flexibility in the location of the driving and driven shafts. iv) Flexible drives are cheap compared to rigid drives . Their initial and maintenance costs are low. |

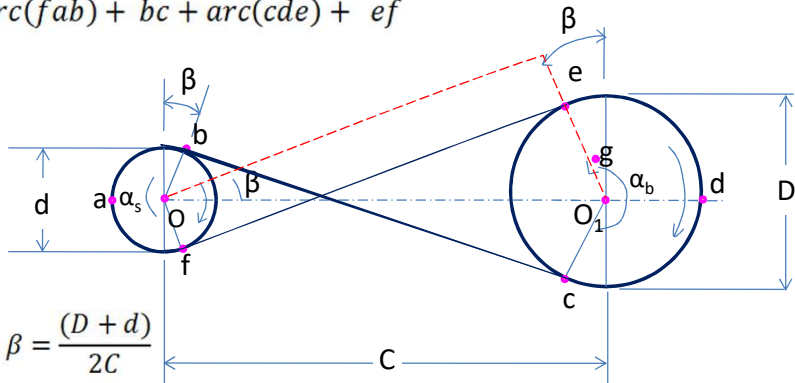
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| | <p>The disadvantages of flexible drives are as follows:</p> <ol style="list-style-type: none"> i) They occupy more space. ii) The velocity ratio is relatively small. |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>Depending on the shape of the cross section, belts are classified as Flat belts and V-belts.</p> |

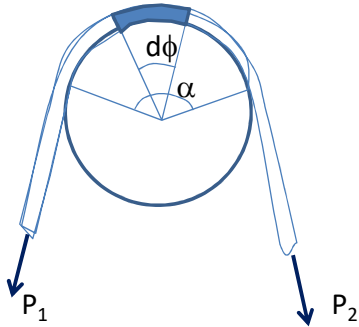
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| | <p>Geometrical Relationships : There are two types of constructions i) Open belt drive</p> $L = \text{arc}(fab) + \overline{bc} + \text{arc}(cde) + \overline{ef}$ |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> |  <p style="text-align: right;">$\alpha_s = (\pi - 2\beta)$</p> $\text{arc}(fab) = \frac{d}{2} \times \alpha_s$ $\sin\beta = \beta = \frac{(D - d)}{2C}$ |

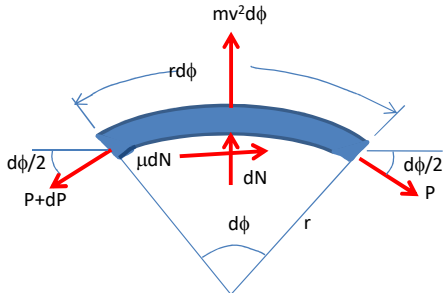
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| | <p>Geometrical Relationships : There are two types of constructions i) Open belt drive</p> $L = \text{arc}(fab) + \overline{bc} + \text{arc}(cde) + \overline{ef}$ |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> |  <p style="text-align: right;">$\alpha_b = (\pi + 2\beta)$</p> $\text{arc}(cde) = \frac{D}{2} \times \alpha_b$ $\sin\beta = \beta = \frac{(D - d)}{2C}$ |

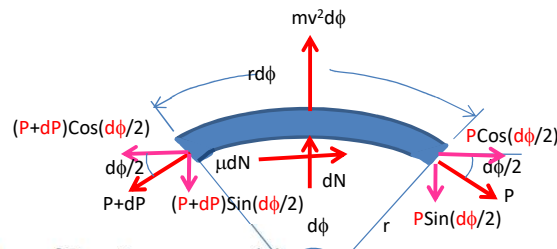
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| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>Geometrical Relationships : There are two types of constructions i) Open belt drive</p> $L = \text{arc}(fab) + \overline{bc} + \text{arc}(cde) + \overline{ef}$  $\overline{bc} = \overline{ef} = C \cos \beta$ |
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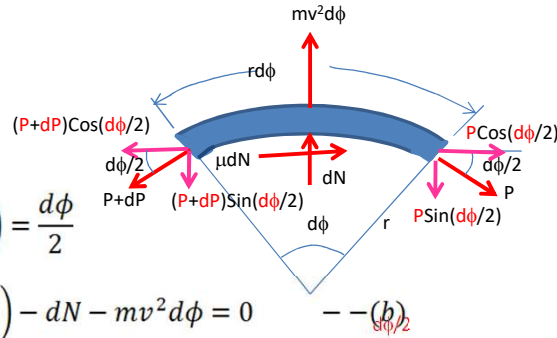
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| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>Geometrical Relationships : There are two types of constructions i) Open belt drive</p> $L = \text{arc}(fab) + \overline{bc} + \text{arc}(cde) + \overline{ef}$  $L = \frac{d}{2} (\pi - 2\beta) + C \cdot \cos \beta + \frac{D}{2} (\pi + 2\beta) + C \cdot \cos \beta$ $L = \frac{\pi}{2} (D + d) + 2C \cdot \cos \beta + \beta (D - d)$ <div style="border: 1px solid black; padding: 5px; width: fit-content; margin: 10px auto;"> <p>Trigonometric Formula</p> $\cos \beta = 1 - 2 \sin^2 \left(\frac{\beta}{2} \right)$ $\cos \beta = 1 - 2 \left(\frac{\beta^2}{4} \right)$ $\sin \beta = \beta = \frac{(D - d)}{2C}$ </div> $L = \frac{\pi}{2} (D + d) + \left[2C \cdot \left(1 - \frac{(D - d)^2}{8C^2} \right) \right] + \left[\frac{(D - d)}{2C} (D - d) \right]$ $L = \frac{\pi}{2} (D + d) + 2C + \frac{(D - d)^2}{4C}$ |
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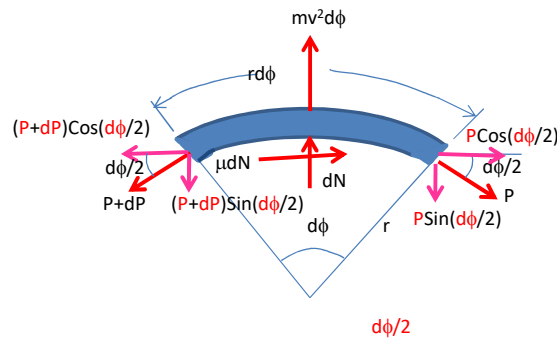
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| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>Geometrical Relationships : ii) Cross belt drive</p> $L = \text{arc}(fab) + \overline{bc} + \text{arc}(cde) + \overline{ef}$  $\sin \beta = \beta = \frac{(D + d)}{2C}$ $\alpha_s = \alpha_b = (\pi + 2\beta)$ $L = \frac{\pi}{2}(D + d) + 2C + \frac{(D + d)^2}{4C}$ |
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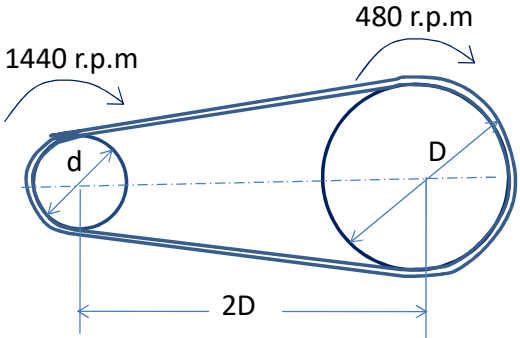
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| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>Analysis of Belt Tensions</p> <p>The forces acting on the element of flat belt are shown in figure. The following notations are used in derivations:</p> <p>P_1 = Belt tension on tight side (N) P_2 = Belt tension on loose side (N) m = mass of one metre length of belt (kg/m) v = belt velocity (m/s) μ = coefficient of friction α = angle of wrap (radians)</p>  |
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| | <p>Analysis of Belt Tensions</p> <p>An element of belt subtended by an angle $d\phi$ is in equilibrium under the action of the following forces :</p>  |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>i) Tensions (P) and (P+dP) on loose and tight sides ii) The normal reaction between the surfaces of belt and pulley (dN) and the frictional force μdN iii) Centrifugal force</p> <p>Centrifugal force = mass X acceleration</p> $= (m \cdot rd\phi) \times \left(\frac{v^2}{r}\right)$ $= (mv^2 d\phi)$ |

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| | <p>Analysis of Belt Tensions</p> <p>Consider the equilibrium of forces in X direction :</p>  |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | $(P + dP)\cos\left(\frac{d\phi}{2}\right) - P\cos\left(\frac{d\phi}{2}\right) - \mu dN = 0 \quad \text{--- (a)}$ $\cos\left(\frac{d\phi}{2}\right) = 1 \text{ and } \sin\left(\frac{d\phi}{2}\right) = \frac{d\phi}{2}$ $P + dP - P - \mu dN = 0$ $dN = \frac{dP}{\mu} \quad \text{--- (c)}$ |

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| | <p>Analysis of Belt Tensions</p> <p>Consider the equilibrium of forces in Y direction :</p>  |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | $\cos\left(\frac{d\phi}{2}\right) = 1 \text{ and } \sin\left(\frac{d\phi}{2}\right) = \frac{d\phi}{2}$ $(P + dP)\sin\left(\frac{d\phi}{2}\right) + P\sin\left(\frac{d\phi}{2}\right) - dN - mv^2 d\phi = 0 \quad \text{--- (b)}$ $P\left(\frac{d\phi}{2}\right) + \left(\frac{dP d\phi}{2}\right) + P\left(\frac{d\phi}{2}\right) - dN - mv^2 d\phi = 0$ $Pd\phi - dN - mv^2 d\phi = 0$ $dN = Pd\phi - mv^2 d\phi$ $\frac{dP}{\mu} = (P - mv^2) d\phi \qquad \frac{dP}{(P - mv^2)} = \mu d\phi$ |

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| | <p>Analysis of Belt Tensions</p>  |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | $\frac{dP}{(P - mv^2)} = \mu d\phi$ <p>Integrate the above equation</p> $\int_{P_2}^{P_1} \frac{dP}{(P - mv^2)} = \mu \int_0^\alpha d\phi$ $[\log(P - mv^2)]_{P_1}^{P_2} = \mu[\phi]_0^\alpha$ $\frac{P_1 - mv^2}{P_2 - mv^2} = e^{\mu\alpha}$ |

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| | <p>The layout of the leather belt drive transmitting 15KW power is shown in Fig.3. The centre distance between the pulleys is twice the diameter of the big pulley. The belt should operate at a velocity of 20m/s approximately and the stress in the belt should not exceed 2.25N/mm². The density of leather is 0.95 gm/cc and the coefficient of friction is 0.35. The thickness of the belt is 5mm. Calculate : i) the diameters of pulleys ii) the length and width of the belt iii) the belt tensions.</p> |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> |  |

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| | <p>Given data :</p> <p>$P = 15 \text{ kW}$, $L = 2D$ $v = 20 \text{ m/s}$ $\sigma = 2.25 \text{ N/mm}^2$</p> <p>$\rho = 0.95 \text{ gm/cc}$ $\mu = 0.35$ $t = 5 \text{ mm}$</p> <p>$n_1 = 1440 \text{ r.p.m}$ $n_2 = 480 \text{ r.p.m}$</p> |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | $v = \frac{\pi d n}{60 \times 10^3} \Rightarrow d = \frac{60 \times 10^3 \times v}{\pi n_1}$ $= \frac{60 \times 10^3 \times 20}{\pi \times 1440} = 265.26 \text{ mm}$ $\approx 270 \text{ mm}$ |

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| | <p>Velocity Ratio $i \propto \frac{D}{d} = \frac{n_1}{n_2}$</p> $D = \frac{n_1}{n_2} \times d = \frac{1440}{480} \times 270 = 810 \text{ mm}$ |
| <p>Dr. M.Raja Roy B.Tech, M.E, Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>Correct belt velocity $V = \frac{\pi d n_1}{60 \times 10^3}$</p> $= \frac{\pi \times 270 \times 1440}{60 \times 10^3} = 20.36 \text{ m/s}$ <hr/> <p>Length of the Belt</p> $L = 2C + \frac{\pi(D+d)}{2} + \frac{(D-d)^2}{4C}$ $= (2 \times 1620) + \frac{\pi(810+270)}{2} + \frac{(810-270)^2}{4 \times 1620}$ $= 4981.46 \text{ mm}$ |

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| | $\alpha_s = 180 - 2 \sin^{-1} \left(\frac{D-d}{2C} \right)$ $= 180 - 2 \sin^{-1} \left(\frac{810-270}{2 \times 1620} \right)$ $= 160.8^\circ \text{ or } 2.81 \text{ radians}$ |
| <p>Dr. M.Raja Roy B.Tech, M.E, Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>Mass of the belt 'm' per metre length</p> $\rho = \frac{m}{V} \Rightarrow m = \rho \cdot V$ $= \rho \cdot A \cdot L$ $= \rho \cdot A \cdot 1$ <div style="display: inline-block; vertical-align: middle; margin-left: 20px;"> $\left\{ \begin{array}{l} V = \text{Volume} \\ A = \text{Area} \\ L = \text{Length} \\ L = 1 \therefore \text{per length} \end{array} \right.$ </div> |

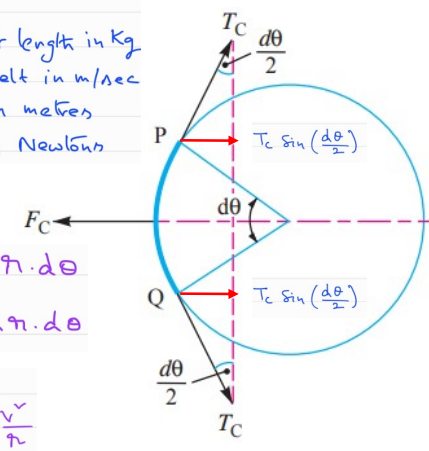
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| | $\rho = 0.95 \text{ gm/cc}$ $= 0.95 \times \frac{\text{kg}}{1000} / \text{cm}^3$ $= 0.95 \times 10^{-3} / \left(\frac{1}{100}\right)^3 \text{ kg/m}^3$ $= 0.95 \times 10^3 \text{ kg/m}$ |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | $A = \left(\frac{b}{1000} \times \frac{5}{1000}\right) \text{ m}^3$ $m = 0.95 \times 10^3 \times \frac{5 \cdot b}{10^6}$ $= 0.95 \times 5 \cdot b \times 10^3 \times 10^{-6}$ $= 4.75 b \times 10^{-3} \text{ kg/m}$ |

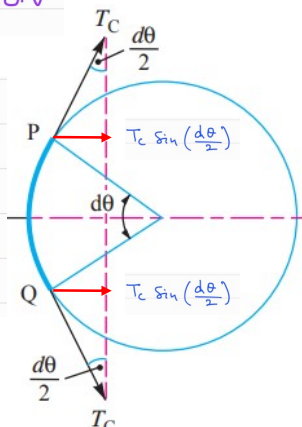
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| | $mv^3 = 4.75 b \times 10^{-3} \times (20.36)^3$ $= 1.97b$ $e^{Mx} = e^{0.35 \times 2.81}$ $= 2.67$ |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | $\frac{P_1 - mv^3}{P_2 - mv^3} = e^{Mx}$ $\frac{P_1 - 1.97b}{P_2 - 1.97b} = 2.67$ $P_1 - 2.67P_2 + 3.29b = 0 \quad \text{--- (i)}$ |

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| | $\sigma = \frac{P_1}{A} \Rightarrow P_1 = \sigma \cdot A$ $= 2.25 \times (5b)$ $P_1 = 11.25b \quad \text{--- (2)}$ |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | $P_1 - P_2 = \frac{1000 \times KW}{v}$ $= \frac{1000 \times 15}{20.36}$ $P_1 - P_2 = 736.74 \quad \text{--- (3)}$ |

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| | $P_1 = 2.67 P_2 + 3.29b = 0 \quad \text{--- (1)}$ $P_1 = 11.25b \quad \text{--- (2)}$ |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | $P_1 - P_2 = 736.74 \quad \text{--- (3)}$ $P_1 = 1428.98 \text{ N} \quad b = 127.02 \text{ mm}$ $P_2 = 692 \text{ N}$ |

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| | <p>Centrifugal Tension :</p> <p>Since the belt continuously runs over the pulleys, therefore, some centrifugal force is caused, whose effect is to increase the tension on both the tight as well as the slack sides. The tension caused by centrifugal force is called centrifugal tension.</p> |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>At lower belt speeds (less than 10 m/s), the centrifugal tension is very small, but at higher belt speeds (more than 10 m/s), its effect is considerable and thus should be taken into account.</p> <p>Consider a small portion PQ of the belt subtending an angle $d\theta$ at the centre of the pulley, as shown in Figure.</p> |

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| | <p>Consider a small portion PQ of the belt subtending an angle $d\theta$ at the centre of the pulley, as shown in Figure.</p> |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>Let</p> <ul style="list-style-type: none"> m = Mass of belt per unit length in Kg v = Linear velocity of belt in m/sec r = Radius of the pulley in metres T_c = Centrifugal Tension in Newtons <p>Length of the belt PA = $r \cdot d\theta$</p> <p>Mass of the belt PA = $m \cdot r \cdot d\theta$</p> <p>Centrifugal force on belt PA</p> $= (m \cdot r \cdot d\theta) \cdot \frac{v^2}{r}$ $F_c = m \cdot d\theta \cdot v^2$  |

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| | <p>Now resolve the forces horizontally</p> $T_c \sin\left(\frac{d\theta}{2}\right) + T_c \sin\left(\frac{d\theta}{2}\right) = m \cdot d\theta \cdot v^2$ |
| <p>Dr. M.Raja Roy B.Tech, M.E, Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>For small values $\sin\left(\frac{d\theta}{2}\right) = \frac{d\theta}{2}$</p> $2 T_c \left(\frac{d\theta}{2}\right) = m \cdot d\theta \cdot v^2$ $T_c = m \cdot v^2$  |

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| | <p><u>Effect of Centrifugal Tension on Power</u></p> <p>Tension on Tight side $T_{t1} = T_1 + T_c$</p> <p>Tension on Slack side $T_{t2} = T_2 + T_c$</p> |
| <p>Dr. M.Raja Roy B.Tech, M.E, Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>Power Transmitted $P = (T_{t1} - T_{t2}) \cdot v$</p> $= [(T_1 + T_c) - (T_2 + T_c)] \cdot v$ $= (T_1 - T_2) \cdot v$ <p>Hence centrifugal tension is not affecting power</p> |

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| | <p>Condition for the transmission of Maximum Power</p> |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>Power Transmitted by belt $P = (T_1 - T_2) \cdot v$ ①</p> <p>$T_1 =$ Tension on tight side (N) $T_2 =$ Tension on slack side (N) $v =$ velocity of belt (m/s)</p> <p>Ratio of driving tensions</p> $\frac{T_1}{T_2} = e^{m\theta} \quad \text{or} \quad T_2 = \frac{T_1}{e^{m\theta}}$ ② |

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| | <p>Substituting ② in ①</p> |
| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | $P = \left(T_1 - \frac{T_1}{e^{m\theta}} \right) \cdot v$ $= T_1 \left(1 - \frac{1}{e^{m\theta}} \right) \cdot v$ $= T_1 \cdot v \cdot C \quad \text{---} \quad \text{③}$ <p>where $C = \left(1 - \frac{1}{e^{m\theta}} \right)$</p> |

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| | <p>Maximum Tension in belt after taking Centrifugal Tension is</p> $T = T_1 + T_c$ $T_1 = T - T_c \quad \text{--- (4)}$ |
| <p>Dr. M.Raja Roy B.Tech, M.E, Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>Substitute (4) in (3)</p> $P = T_r \cdot v \cdot c$ $= (T - T_c) \cdot v \cdot c$ $= (T - m \cdot v^2) \cdot v \cdot c$ $= (T \cdot v - mv^3) \cdot c$ |

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| | <p>For maximum power differentiate Power with velocity and equal to zero</p> $\frac{dP}{dv} = 0$ |
| <p>Dr. M.Raja Roy B.Tech, M.E, Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | $\frac{d}{dv} (T \cdot v - mv^3) \cdot c = 0$ $T - 3mv^2 = 0 \quad \text{--- (5)}$ <p>velocity of Max Power $v = \sqrt{\frac{T}{3 \cdot m}}$</p> |

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| <p>Dr. M.Raja Roy B.Tech,M.E,Ph.D</p> <p>www.mrrtechnical.co.in www.rajaroy.co.in www.youtube.com/rajaroym</p> | <p>From (5) $T - 3T_c = 0 \quad \therefore T_c = mv^2$</p> $T_c = \frac{T}{3}$ <p>For Transmissibility Max Power $\frac{1}{3} g \text{ the}$</p> <p>Max tension is absorbed at centrifugal tension.</p> |
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Example A leather belt 9 mm × 250 mm is used to drive a cast iron pulley 900 mm in diameter at 336 r.p.m. If the active arc on the smaller pulley is 120° and the stress in tight side is 2 MPa, find the power capacity of the belt. The density of leather may be taken as 980 kg/m³, and the coefficient of friction of leather on cast iron is 0.35.

Solution. Given: $t = 9 \text{ mm} = 0.009 \text{ m}$; $b = 250 \text{ mm} = 0.25 \text{ m}$; $d = 900 \text{ mm} = 0.9 \text{ m}$; $N = 336 \text{ r.p.m}$; $\theta = 120^\circ = 120 \times \frac{\pi}{180} = 2.1 \text{ rad}$; $\sigma = 2 \text{ MPa} = 2 \text{ N/mm}^2$; $\rho = 980 \text{ kg/m}^3$; $\mu = 0.35$

We know that the velocity of the belt,

$$v = \frac{\pi d N}{60} = \frac{\pi \times 0.9 \times 336}{60} = 15.8 \text{ m/s}$$

and cross-sectional area of the belt,

$$a = b.t = 9 \times 250 = 2250 \text{ mm}^2$$

\therefore Maximum or total tension in the tight side of the belt,

$$T = T_{t1} = \sigma.a = 2 \times 2250 = 4500 \text{ N}$$

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We know that mass of the belt per metre length,

$$m = \text{Area} \times \text{length} \times \text{density} = b.t.l.\rho = 0.25 \times 0.009 \times 1 \times 980 \text{ kg/m} \\ = 2.2 \text{ kg/m}$$

\therefore Centrifugal tension,

$$*T_C = m.v^2 = 2.2 (15.8)^2 = 550 \text{ N}$$

and tension in the tight side of the belt,

$$T_1 = T - T_C = 4500 - 550 = 3950 \text{ N}$$

Let $T_2 =$ Tension in the slack side of the belt.

We know that

$$2.3 \log \left(\frac{T_1}{T_2} \right) = \mu.\theta = 0.35 \times 2.1 = 0.735$$

$$\log \left(\frac{T_1}{T_2} \right) = \frac{0.735}{2.3} = 0.3196 \quad \text{or} \quad \frac{T_1}{T_2} = 2.085$$

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$$T_2 = \frac{T_1}{2.085} = \frac{3950}{2.085} = 1895 \text{ N}$$

We know that the power capacity of the belt,

$$P = (T_1 - T_2) v = (3950 - 1895) 15.8 = 32\,470 \text{ W} = 32.47 \text{ kW} \text{ Ans.}$$

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